

Lecture 14

Timing Constraints & Timing Analysis

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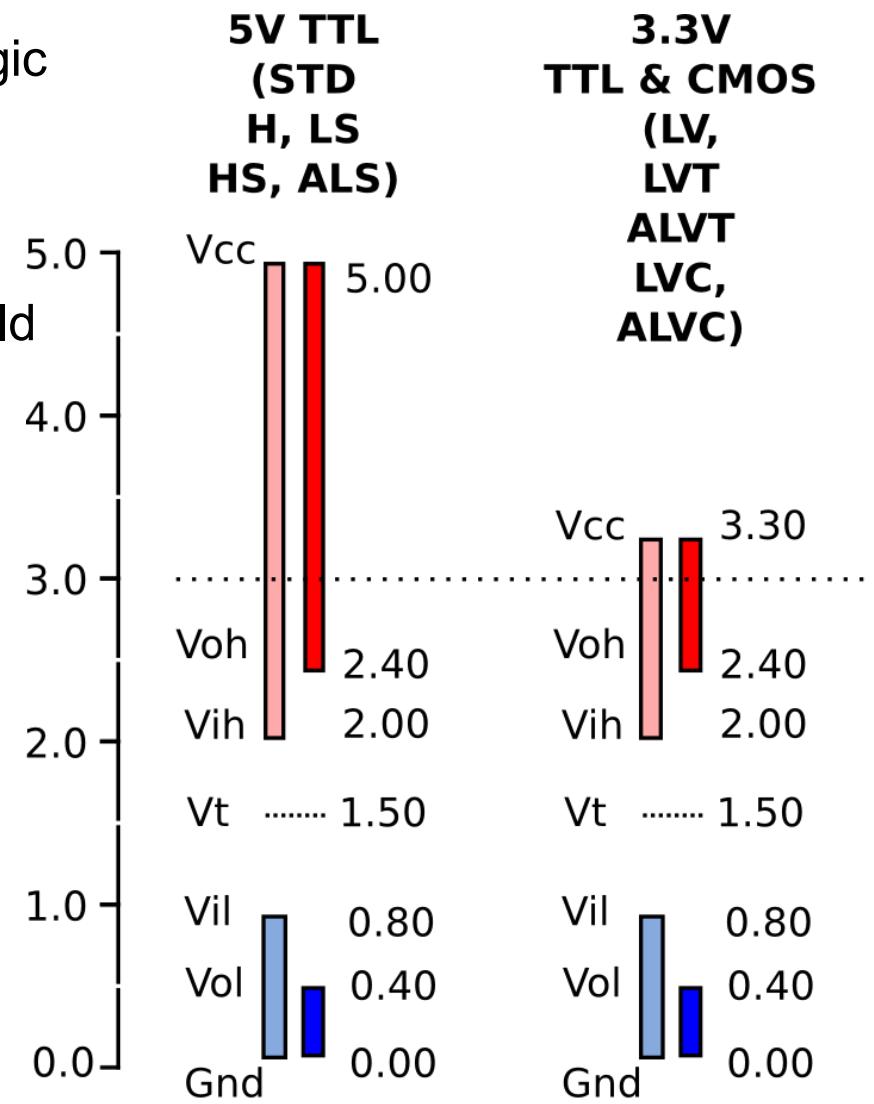
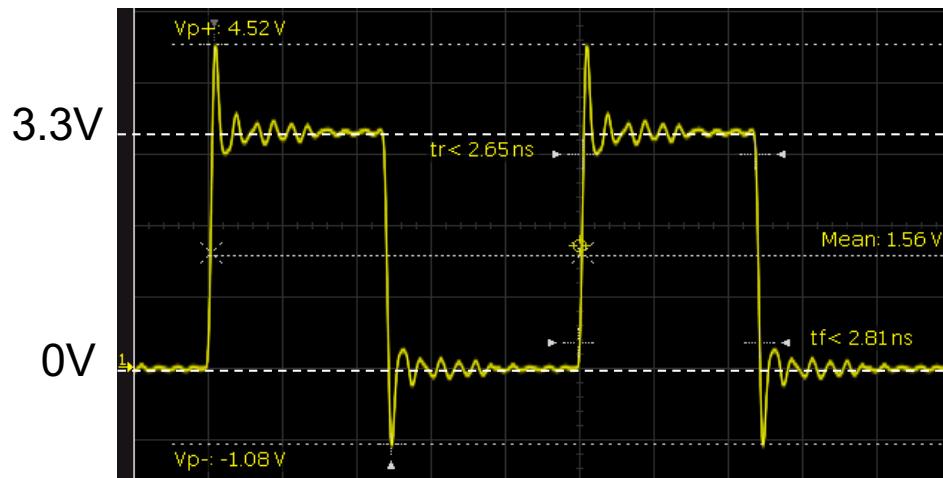
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Lecture Objectives

- ◆ Appreciate the difference between theoretical and real digital signals
- ◆ Understand the low and high logic level thresholds for input and output digital signals
- ◆ Understand the meaning of noise margin and why they are needed
- ◆ Explain the meaning of setup and hold times in flipflops
- ◆ Explain how data is sent between two digital systems using a synchronous bit-serial protocol
- ◆ Investigate the timing constraints in a transmission system
- ◆ Explore the **TimeQuest** timing analyser used in the Quartus system

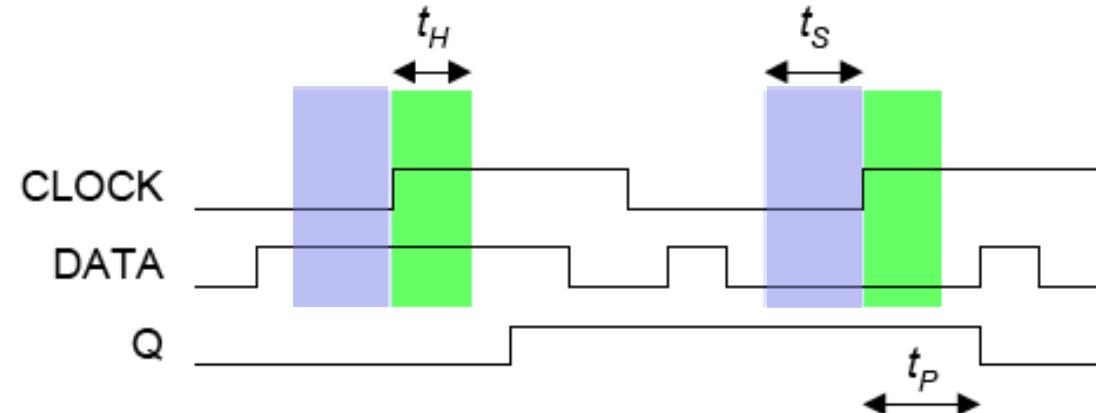
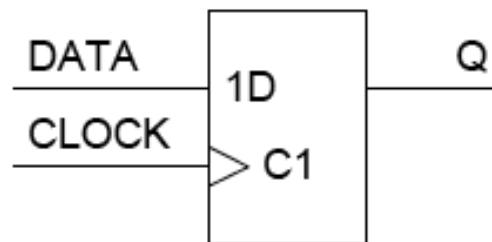
Typical digital signal

- Real digital signals are generally far from ideal.
- Shown here is a 4MHz digital signal using 3.3V logic as measured on a digital oscilloscope.
- There are overshoots and undershoots in voltage levels and finite rise and fall times.
- That's why logic circuits have well-defined threshold voltages for high and low levels as shown on the right.
- For 3.3V logic, $V_{oh} \geq 2.4V$ and $V_{ih} \geq 2V$, therefore the high level margin (noise margin) is 0.4V



Setup and Hold Times

The DATA input to a flipflop or register must not change at the same time as the CLOCK.

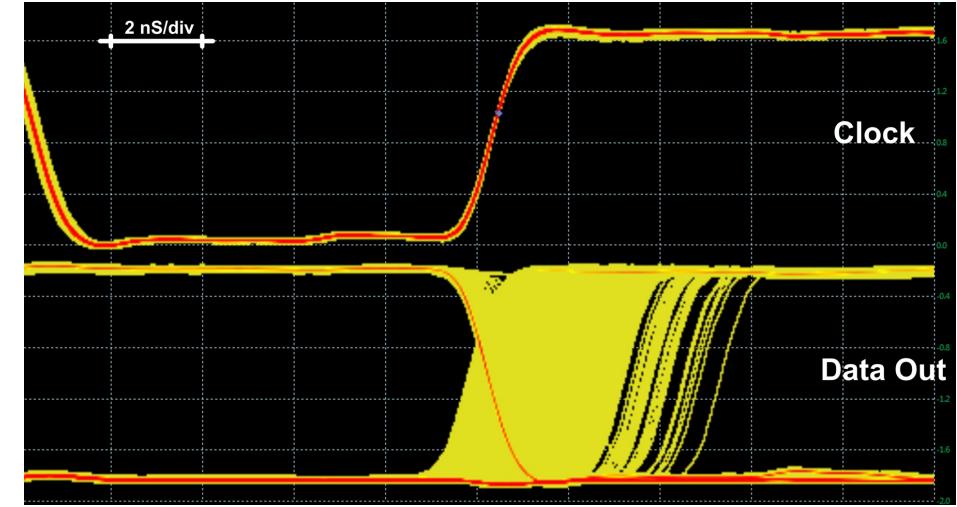
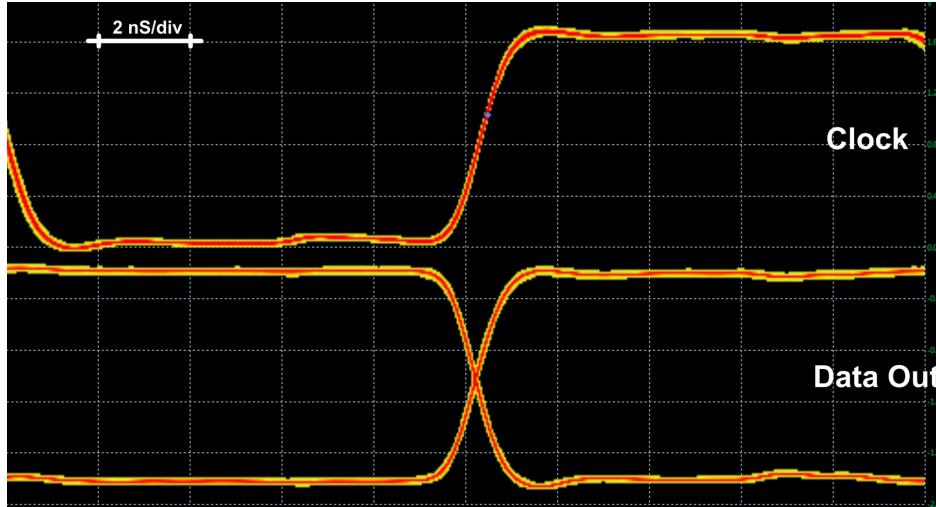


Setup Time: DATA must reach its new value at least t_S before the CLOCK \uparrow edge.

Hold Time: DATA must be held constant for at least t_H after the CLOCK \uparrow edge.

- Typical values for a register: $t_S = 5$ ns, $t_H = 3$ ns (discrete logic/ I/O circuit)
 $t_S = -50$ ps, $t_H = 0.2$ ns (internal LE)
- The setup and hold times define a window around each CLOCK \uparrow edge within which the DATA **must not change**.
- If these requirements are not met, the Q output may oscillate for many nanoseconds before settling to a stable value.

Setup time violation and metastability



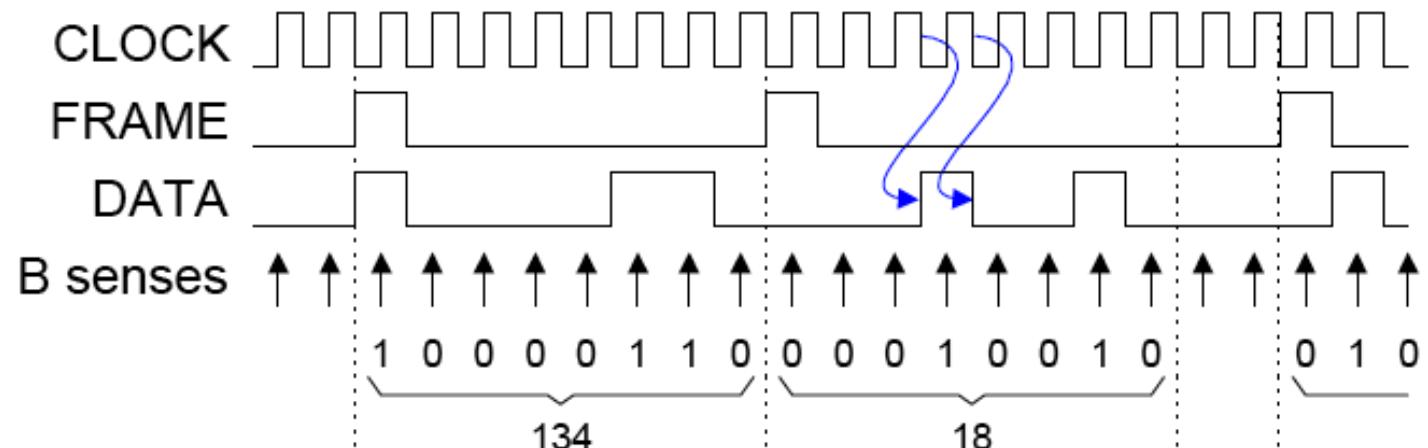
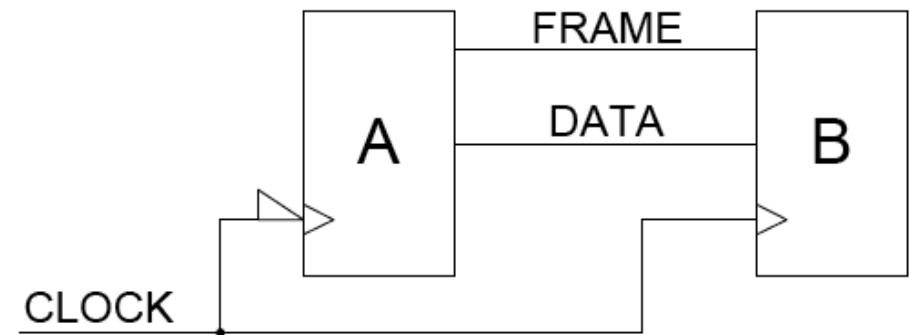
- ◆ No setup time violation
- ◆ Input data arrives earlier than t_s before rising edge of Clock
- ◆ Data Out changes cleanly to either 0 or 1

- ◆ Set up time violation
- ◆ Input data arrives within the setup time window t_s
- ◆ Data Out becomes undefined (0 or 1 or somewhere in between) for a random period time before settling down to either 0 or 1
- ◆ This can cause the digital circuit to fail

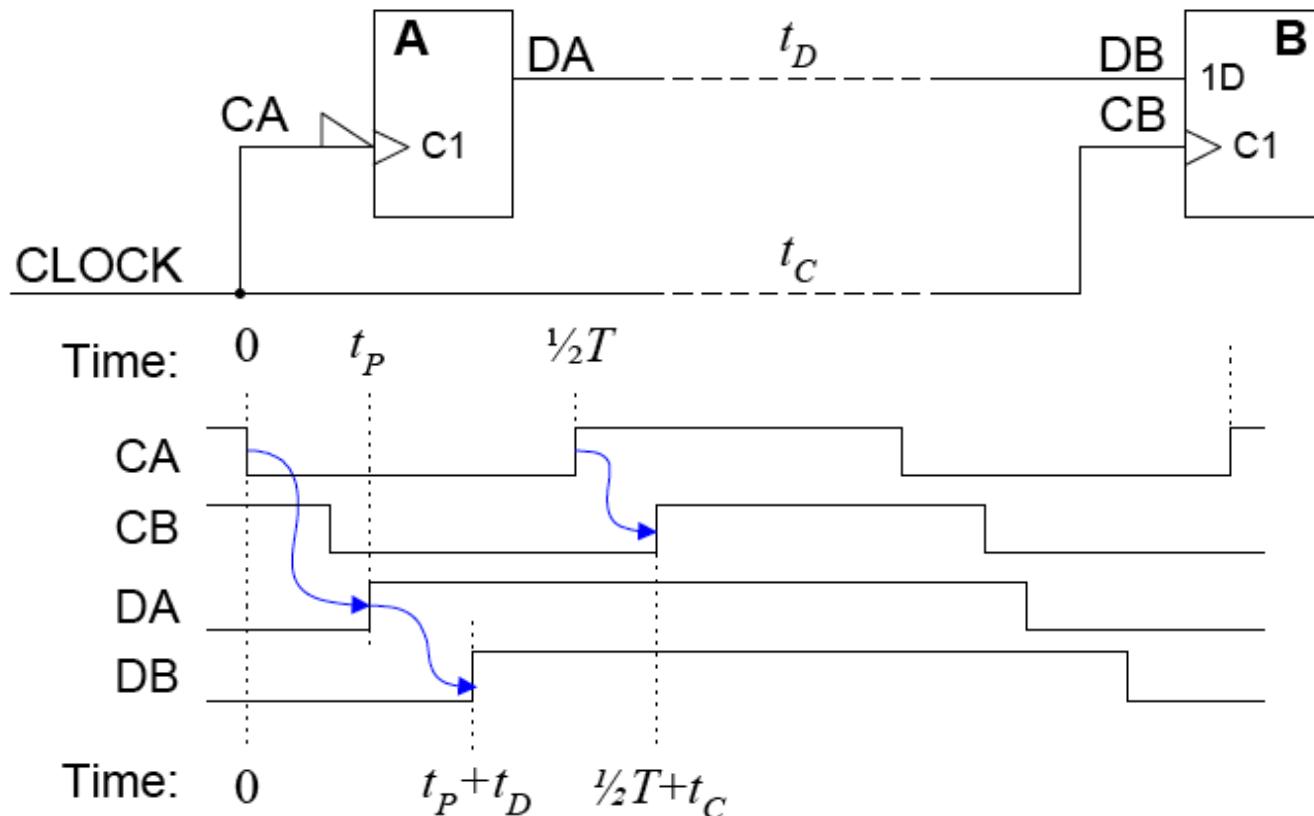
Synchronous Bit-Serial Transmission

Transmitting 8 bit values from A to B:

- ◆ FRAME indicates the first bit of each value; the other 7 bits follow on consecutive clock cycles. The FRAME signal is often called a **frame sync pulse**.
- DATA changes on the *falling* CLOCK edge
- Propagation delays are often omitted from diagram.
- DATA is sensed by system B on the *rising* CLOCK edge to maximise tolerance to timing errors. We must always clock a flipflop at a time when its DATA input is not changing.



Timing Specifications



For Device B:

- ◆ Data input changes at time $t_P + t_D$
- ◆ Clock input changes ↑ at time $\frac{1}{2}T + t_C$

t_P

Propagation delay for device A.

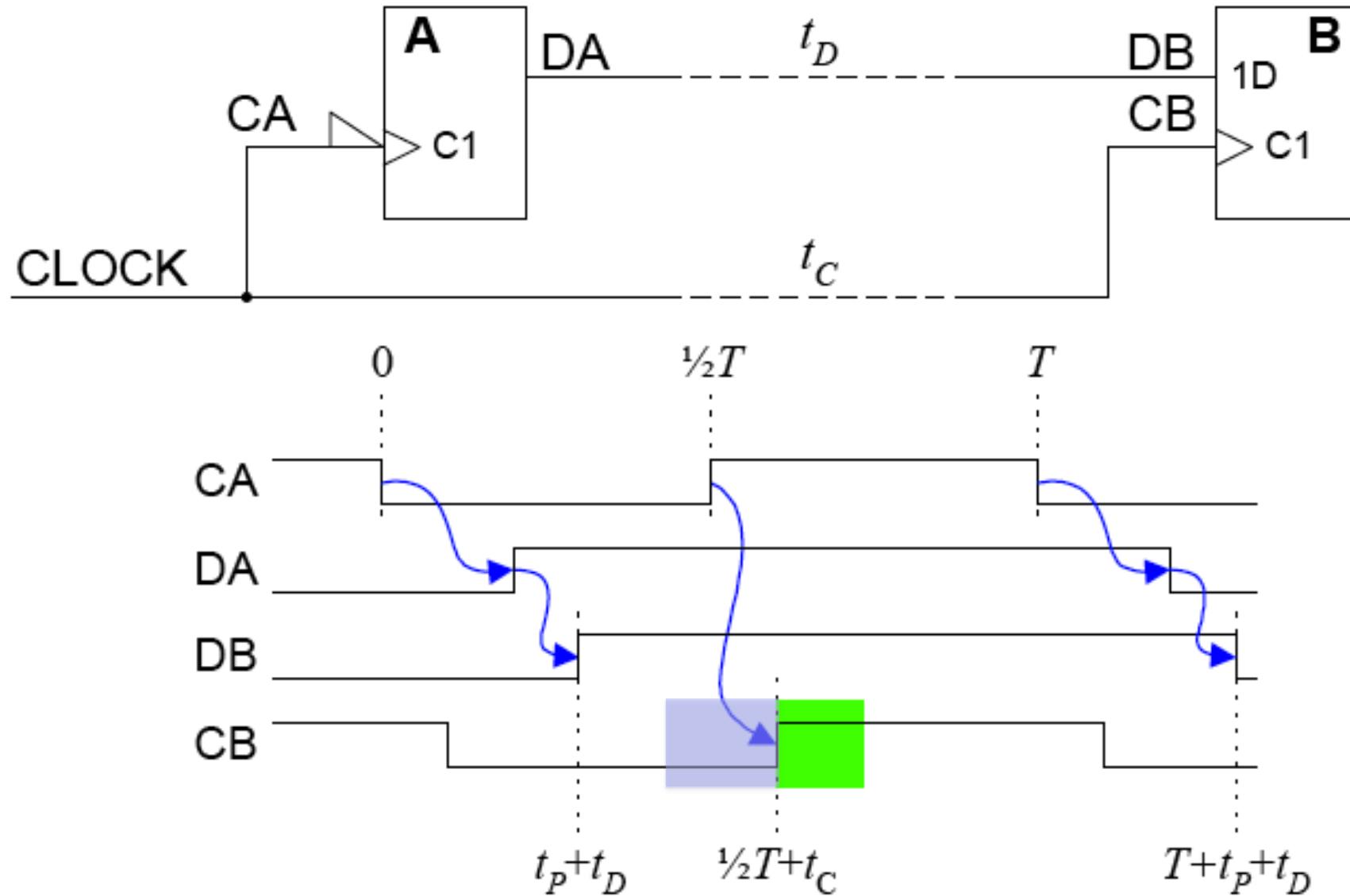
T

Clock Period.

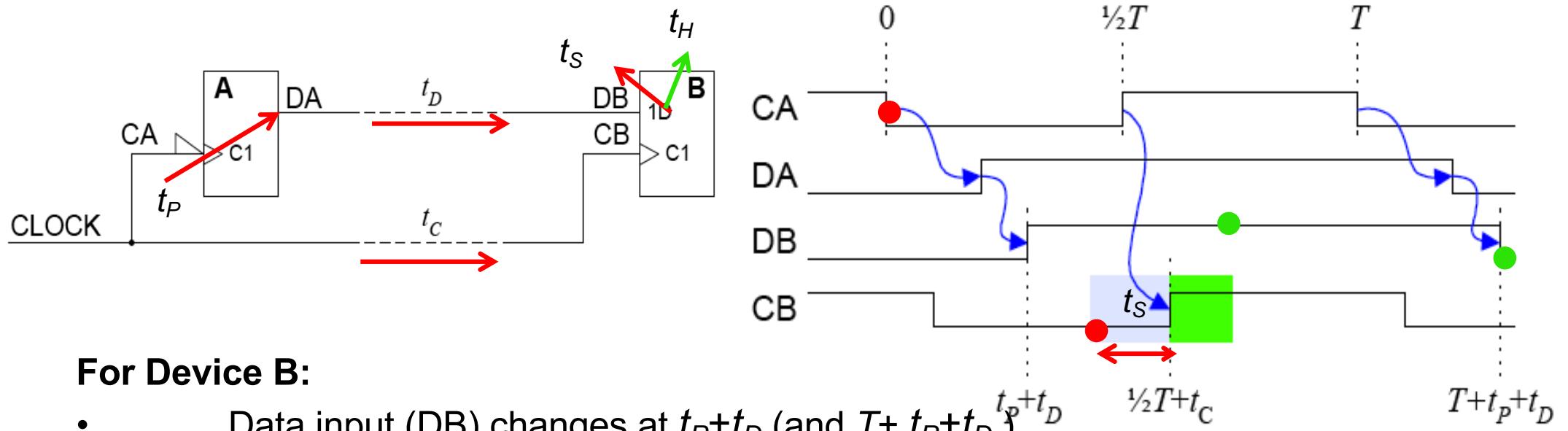
t_C, t_D

Transmission line delays for CLOCK and DATA

Timing Constraints (1)



Timing Constraints (2)



For Device B:

- Data input (DB) changes at t_P+t_D (and $T+t_P+t_D$)
- Clock \uparrow (CB) at time $\frac{1}{2}T+t_C$

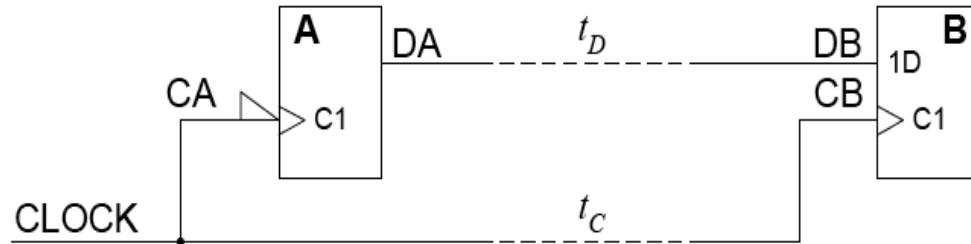
For reliable operation:

- Setup Requirement: $t_P + t_D + t_S < \frac{1}{2}T + t_C$
- Hold Requirement: $\frac{1}{2}T + t_C + t_H < T + t_P + t_D$

Get a pair of inequalities for each flipflop/register in a circuit.

You never get both t_S and t_H in the same inequality.

Example



For a given DSP processor:

$$0 < t_P < 10 \text{ ns}, t_S = 5 \text{ ns}, t_H = 3 \text{ ns}$$

Suppose differential delay: $-10 < (t_D - t_C) < +10$

Find maximum CLOCK frequency (min CLOCK period):

$$\text{◆} \max(t_P + t_D) + t_S < \min(\frac{1}{2}T + t_C)$$

$$10 + 10 + 5 < \frac{1}{2}T + 0$$

$$\frac{1}{2}T > 25$$

$$\boxed{\text{Setup Requirement: } t_P + t_D + t_S < \frac{1}{2}T + t_C}$$

$$(t_D = 10, t_C = 0)$$

$$\Rightarrow T > 50 \text{ ns}$$

$$\text{◆} \max(\frac{1}{2}T + t_C) + t_H < \min(T + t_P + t_D)$$

$$\frac{1}{2}T + 10 + 3 < T + 0 + 0$$

$$\frac{1}{2}T > 13$$

$$\boxed{\text{Hold Requirement: } \frac{1}{2}T + t_C + t_H < T + t_P + t_D}$$

$$(t_D = 0, t_C = 10)$$

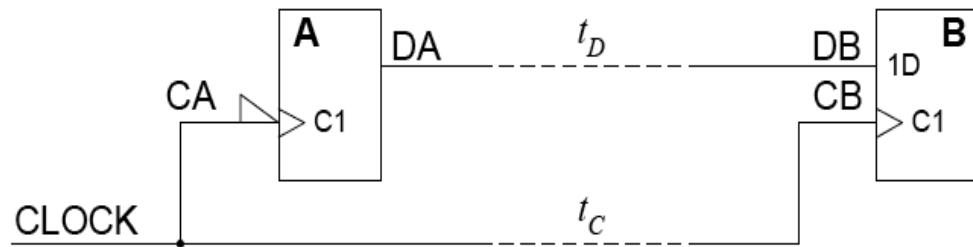
$$\Rightarrow T > 26 \text{ ns}$$

$$\text{◆ Hence } f_{\text{CLOCK}} < 1/50 \text{ ns} = 20 \text{ MHz}$$

◆ To test for worst case: make the left side of the inequality as big as possible and the right side as small as possible.

Propagation Delay Constraint Inequalities

When do they arise?



Whenever a flipflop's clock and data input signals originate from the same ultimate source. Here CB and DB both originate from CLOCK. You normally get two inequalities for each flipflop in a circuit.

Relationship between setup and hold inequalities:

- Setup Requirement: $t_P + t_D + t_S < \frac{1}{2}T + t_C$
- Hold Requirement: $\frac{1}{2}T + t_C + t_H < t_P + t_D + T$

Are both t_S and t_H ever in the same inequality?

- No.

How do you decide to take the max or the min?

- For a $<$, take max of everything on the left and min of everything on the right.
- max = most positive: for example, $\max(-7, -2) = -2$

IMPORTANT:
These inequalities applies
ONLY to this circuit.
IT IS NOT UNIVERSAL!

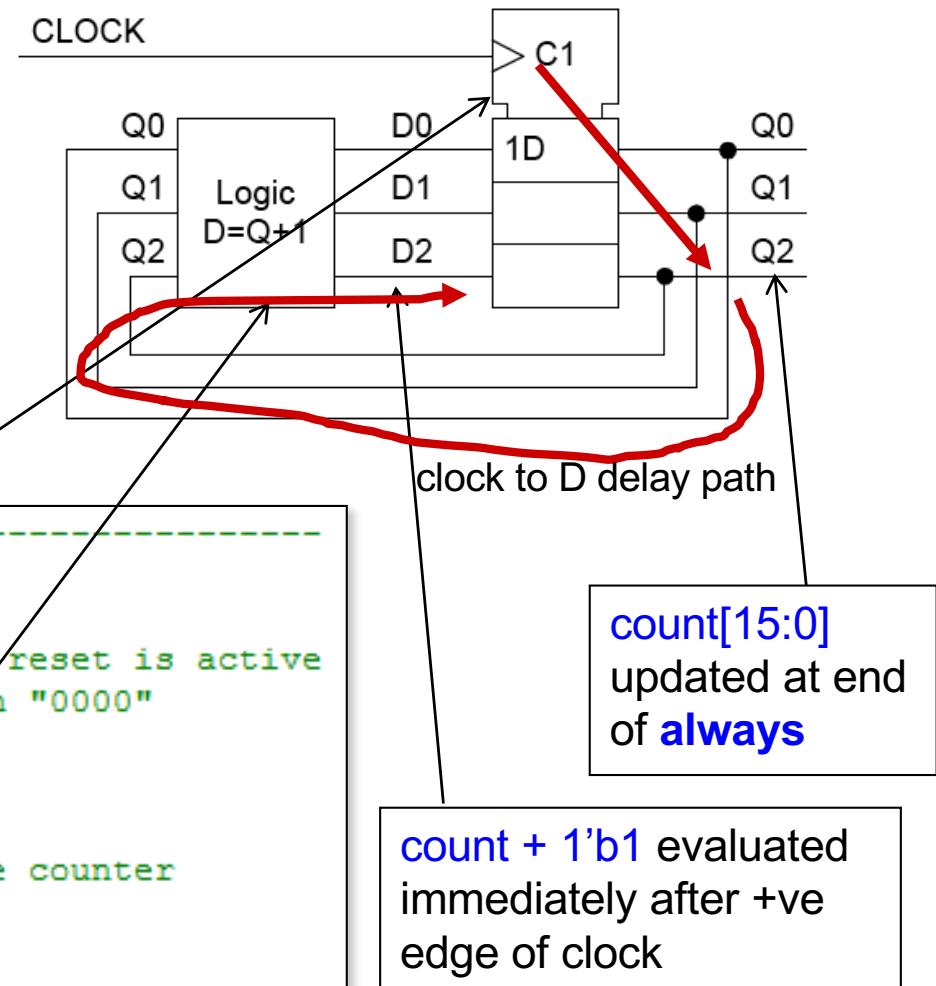
The 16-bit up-counter

```
module counter (
    clock,          // Clock input to the design
    reset,          // active high, synchronous Reset input
    enable,         // Active high enable signal for counter
    count           // 4 bit vector output of the counter
);               // End of port list

//-----Input Ports-----
input clock;
input reset;
input enable;

//-----Output Ports-----
output [15:0] count;
//----- Main Body of the module -
//----- All the
//----- always @ (posedge clock) begin
    // At every rising edge of clock we check if reset is active
    // If active, we load the counter output with "0000"
    if (reset == 1'b1) begin
        count <= 16'b0;
    end
    // If enable is active, then we increment the counter
    else if (enable == 1'b1) begin
        count <= count + 1'b1;
    end
end // End of Block

endmodule // End of Module counter
```



TimeQuest Report (1) - Fmax

- TimeQuest Timing Analyzer
 - Summary
 - SDC File List
 - Clocks
 - Slow 1200mV 85C Model
 - Fmax Summary**
 - Timing Closure Recommendations
 - Setup Summary
 - Hold Summary
 - Recovery Summary
 - Removal Summary
 - Minimum Pulse Width Summary
 - Worst-Case Timing Paths
 - Datasheet Report
 - Metastability Report
 - Slow 1200mV 0C Model
 - Fast 1200mV 0C Model
 - Multicorner Timing Analysis Summary
 - Multicorner Datasheet Report Summary
 - Advanced I/O Timing
 - Clock Transfers
 - Report TCCS
 - Report RSKM
 - Unconstrained Paths
 - Messages

$$F_{max} = 1/(t_{c-q} + t_p + t_{setup})$$

Slow 1200mV 0C Model Fmax Summary

	Fmax	Restricted Fmax	Clock Name
1	498.5 MHz	250.0 MHz	clock

Slow 1200mV 85C Model Fmax Summary

	Fmax	Restricted Fmax	Clock Name
1	438.79 MHz	250.0 MHz	clock

Slow 1200mV 85C Model Setup Summary

	Clock	Slack	End Point TNS
1	clock	17.721	0.000

clock to D delay path

count[15:0] updated at end of always

count + 1'b1 evaluated immediately after +ve edge of clock

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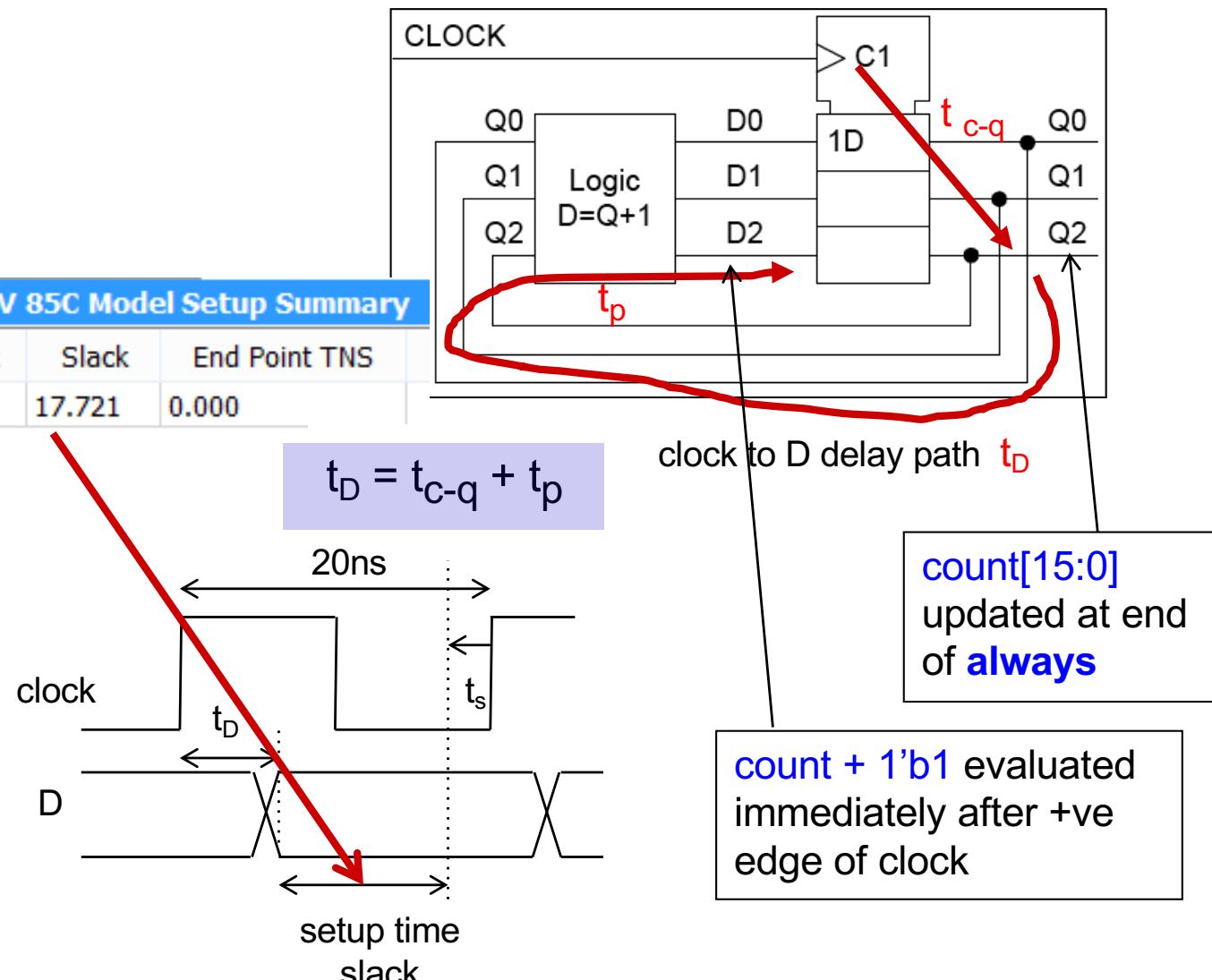
EE2 Circuits & Systems

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TimeQuest Report (2) – Setup Summary

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TimeQuest Report (2) – Hold Summary

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	Clock	Slack	End Point TNS
1	clock	0.570	0.000

